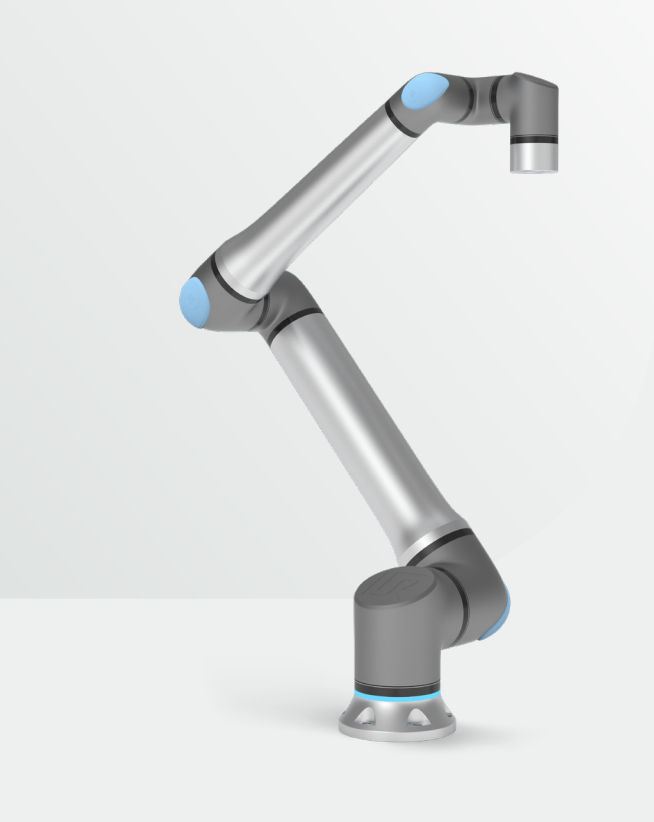




UR20

General specification

Payload	20 kg (44,1 lbs) in the entire workspace
Reach	1750 mm (68,9 in)
Degrees of freedom	6 rotating joints
Programming	12 inch touchscreen with PolyScope graphical user interface
Power consumption (average)	
Maximum power	750 W
Moderate operating settings	300 W
Operating temperature range	Ambient temperature: 0-50°C (32-122°F)
Safety functions	17 configurable safety functions
In compliance with	EN ISO 13849-1 (PLd Category 3) and EN ISO 10218-1

UR20 arm

Performance

Force sensing, tool flange/torque sensor	Force, x-y-z	Torque, x-y-z
Range	200,0 N	20,0 Nm
Precision	5,5 N	0,2 Nm
Accuracy	10,0 N	0,1 Nm

Movement

Axis movement	Working range	Maximum speed
Base	± 360°	± 120°/s
Shoulder	± 360°	± 120°/s
Elbow	± 360°	± 150°/s
Wrist 1	± 360°	± 210°/s
Wrist 2	± 360°	± 210°/s
Wrist 3	± 360°	± 210°/s



UR20

Technical Specification

The UR20, the first of our next-generation high performance cobots, has been redesigned from the ground up to provide up to 30% more speed and torque, advanced motion control capabilities, and first-class user experience.

UR cobots bring incredible versatility and unparalleled ease of use to your applications. The UR20 is no exception - its 20 kg payload and 1750 mm reach make it an ideal match for applications ranging from palletizing to machine loading.

Updated October 2023.

Features

IP classification	IP65 water protection
Noise	< 65 dB(A)
Arm mounting	Any orientation
I/O Ports	
Digital In	2
Digital Out	2
Analog In	2
Tool I/O power supply voltage	12/24 V
Tool I/O power supply	2 A (Dual pin), 1 A (Single pin)

Physical

Footprint	Ø 245 mm; 6 x M10, 60° 105 mm center
Materials	Aluminum, plastic, steel
Tool flange	EN ISO-9409-1-80-6-M8
Connector type	M8 M8 8-pin female
Cable length (robot arm)	6 m (236 in)
Weight including cable	64 kg (141,1 lbs)
Humidity	≤ 90% RH (non-condensing)

Contact

Universal Robots A/S
Energivej 25
5260 Odense
Denmark

+45 89 93 89 89
sales@universal-robots.com
universal-robots.com

3-Position Enabling Teach Pendant

Features

IP classification	IP54 water protection
Humidity	≤ 90% RH (non-condensing)
Display resolution	1280 x 800 pixels

Physical

Materials	Plastic
Teach pendant size (W x H x D)	300 mm x 231 mm x 50 mm (11,8 in x 9,1 in x 1,97 in)
Weight	1,8 kg (3.961 lbs) including 1 m of teach pendant cable
Cable length	4,5 m (177,17 in)

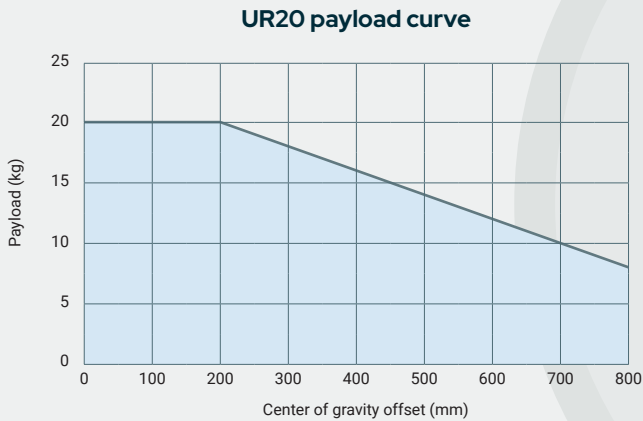
Control Box

Features

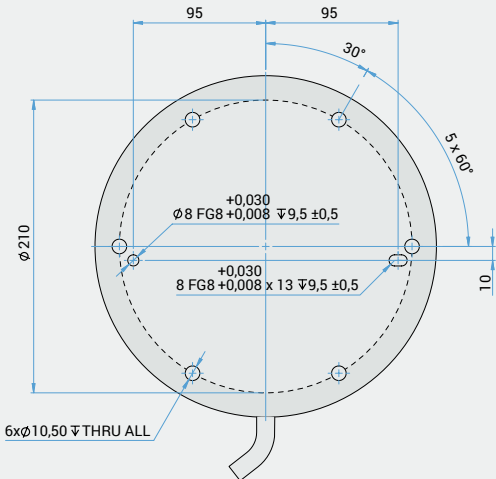
IP Classification	IP44 water protection
Humidity	≤ 90% RH (non-condensing)
I/O Ports	
Digital In	16
Digital Out	16
Analog In	2
Analog Out	2
Quadrature digital inputs	4
I/O Power Supply	24V, 2A
Communication	500 Hz Control frequency Modbus TCP PROFINET, PROFIsafe (optional) Ethernet/IP USB 2.0, USB 3.0 ROS/ROS2 driver support (optional, open source) Injection Molding Machine Interface (IMMI, optional)
Power Source	100-240 VAC, 47-440 Hz

Physical

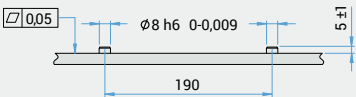
Control Box Size (W x H x D)	460 mm x 449 mm x 254 mm (18,2 in x 17,6 in x 10 in)
Weight	12 kg (26,5 lbs)
Materials	Powder coated steel



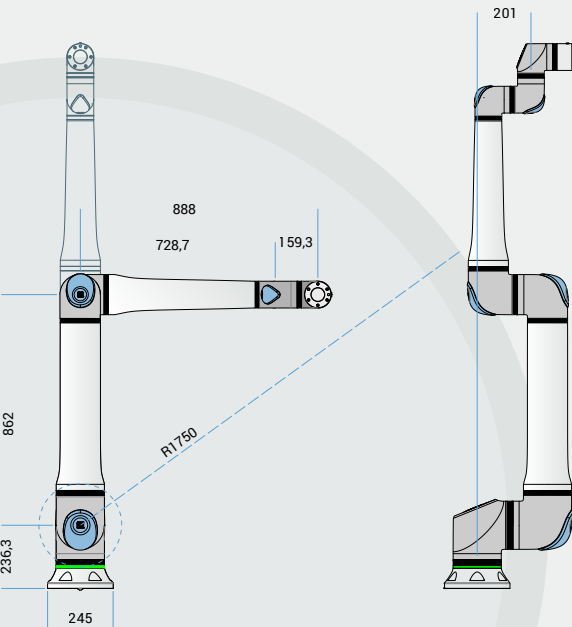
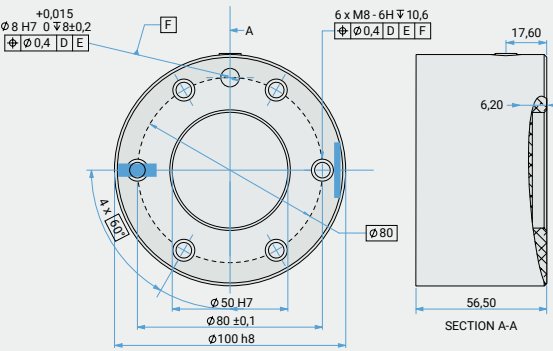
Recommended hole pattern for robot base



Mounting plate with pins for robot base



UR20 tool flange



UNLESS OTHERWISE SPECIFIED:
Dimensions are in millimeters. Tolerance ± 0,1 mm ± 0,5°



UR20

General specification

Payload	20 kg (44.1 lbs) in the entire workspace
Reach	68.9 in
Degrees of freedom	6 rotating joints
Programming	12 inch touchscreen with PolyScope graphical user interface
Power consumption (average)	
Maximum power	750 W
Moderate operating settings	300 W
Operating temperature range	Ambient temperature: 0-50°C (32-122°F)
Safety functions	17 configurable safety functions
In compliance with	EN ISO 13849-1 (PLd Category 3) and EN ISO 10218-1

UR20 arm

Performance

Force sensing tool flange/torque sensor	Force, x-y-z	Torque, x-y-z
Range	200.0 N	20.0 Nm
Precision	5.5 N	0.2 Nm
Accuracy	10.0 N	0.1 Nm

Movement

Typical TCP speed	2 m/s	
Pose repeatability per ISO 9283	± 0.1 mm	
Axis movement	Working range	Maximum speed
Base	± 360°	± 120°/s
Shoulder	± 360°	± 120°/s
Elbow	± 360°	± 150°/s
Wrist 1	± 360°	± 210°/s
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UR20

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Updated October 2023.

Features

IP classification	IP65 water protection
Noise	< 65 dB(A)
Arm mounting	Any orientation
I/O Ports	
Digital In	2
Digital Out	2
Analog In	2
Tool I/O power supply voltage	12/24 V
Tool I/O power supply	2 A (Dual pin), 1 A (Single pin)

Physical

Footprint	Ø 9.65 in 6 x M10 60° 4.13 in center
Materials	Aluminum, plastic, steel
Tool flange	EN ISO-9409-1-80-6-M8
Connector type	M8 M8 8-pin female
Cable length (robot arm)	236 in
Weight including cable	141.1 lbs
Humidity	≤ 90% RH (non-condensing)

Contact

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3-Position Enabling Teach Pendant

Features

IP classification	IP54 water protection
Humidity	≤ 90% RH (non-condensing)
Display resolution	1280 x 800 pixels

Physical

Materials	Plastic
Teach pendant size (W x H x D)	11.8 in x 9.1 in x 1.97 in
Weight	3.961 lbs including 1 m of teach pendant cable
Cable length	177.17 in

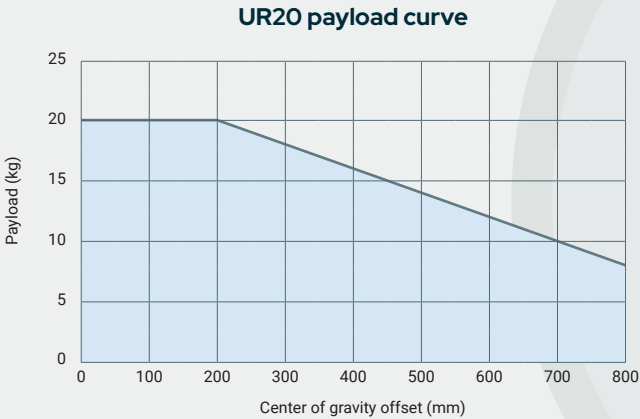
Control Box

Features

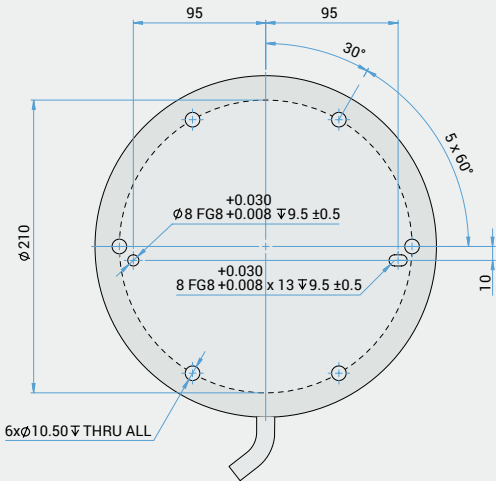
IP Classification	IP44 water protection
Humidity	≤ 90% RH (non-condensing)
I/O Ports	
Digital In	16
Digital Out	16
Analog In	2
Analog Out	2
Quadrature digital inputs	4
I/O Power Supply	24V, 2A
Communication	
500 Hz Control frequency	
Modbus TCP	
PROFINET, PROFIsafe (optional)	
Ethernet/IP	
USB 2.0, USB 3.0	
ROS/ROS2 driver support (optional, open source)	
Injection Molding Machine Interface (IMMI, optional)	
Power Source	100-240 VAC, 47-440 Hz

Physical

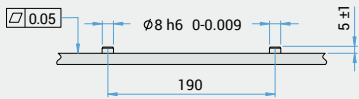
Control Box Size (W x H x D)	18.2 in x 17.6 in x 10 in
Weight	26.5 lbs
Materials	Powder coated steel



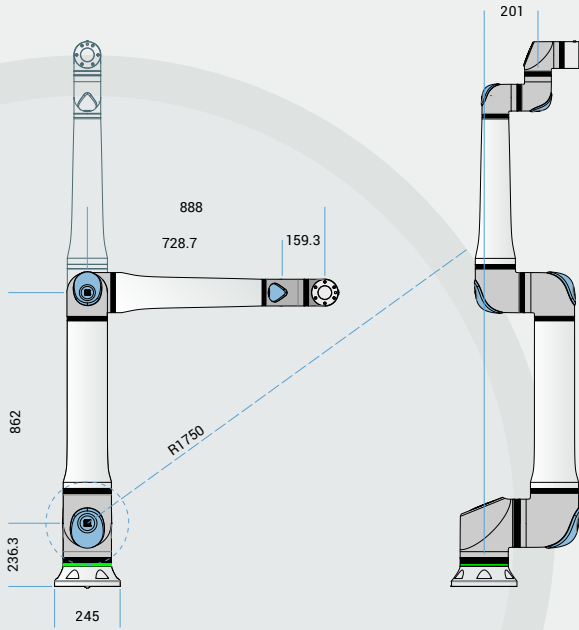
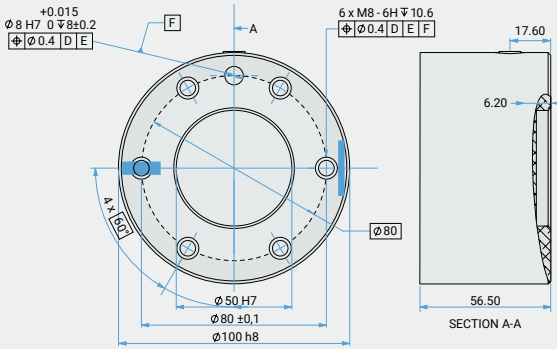
Recommended hole pattern for robot base



Mounting plate with pins for robot base



UR20 tool flange



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Dimensions are in millimeters. Tolerance ± 0.1 mm ± 0.5°